

PROBLEM SET 6 SOLUTIONS

① a) We have:

$$S = \int d^4x \left\{ -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} + \frac{1}{2} m^2 A_\mu A^\mu \right\}$$

The terms involving time derivatives in $-\frac{1}{4} F_{\mu\nu} F^{\mu\nu}$ are

$$\begin{aligned} & -\frac{1}{4} F_{0i} F^{0i} - \frac{1}{4} F_{i0} F^{i0} \\ &= \frac{1}{2} (F_{0i})^2 \\ &= \frac{1}{2} (\partial_0 A_i - \partial_i A_0)^2 = \frac{1}{2} (\partial_0 A^i + \partial_i A^0)^2 \end{aligned} \quad \begin{matrix} \text{remember } A_0 = A^0 \\ A_i = -A^i \end{matrix}$$

$$\text{So } \frac{\delta L}{\delta \dot{A}_0} = 0 \quad \text{and} \quad \frac{\delta L}{\delta \dot{A}^i} = \partial_0 A^i + \partial_i A^0$$

Thus: $\boxed{\pi^0 = 0}$ and $\boxed{\pi^i = \partial_0 A^i + \partial_i A^0}$ (or $-\partial_0 A_i + \partial_i A_0$)

If $\pi^0 = 0$ identically, then $[A^0, \pi^0]$ must also be zero.

b) For A^0 , the equation of motion can be derived using:

$$S = \int d^4x \left\{ \frac{1}{2} (\partial_0 A^i + \partial_i A^0)^2 + \frac{1}{2} m^2 (A^0)^2 + \text{terms with no } A^0 \right\}$$

\therefore If we take $A^0 + \delta A^0$

$$\begin{aligned} \delta S &= \int d^4x \left\{ \partial_i \delta A^0 (\partial_0 A^i + \partial_i A^0) + m^2 A^0 \delta A^0 \right\} \\ &= \int d^4x \delta A^0 \left\{ -\partial_i (\partial_0 A^i + \partial_i A^0) + m^2 A^0 \right\} \end{aligned}$$

The equation of motion is thus

$$\boxed{m^2 A^0 - \partial_i (\partial_0 A^i + \partial_i A^0) = 0}$$

This is equivalent to:

$$A^0 = \frac{1}{m^2} \partial_i \pi^i$$

c) To derive the Hamiltonian, we write:

$$\begin{aligned}
 H &= \int d^3x \dot{A}^i \pi^i - L && \text{now, eliminate } \dot{A}^i \text{ via} \\
 &= \int d^3x \left(\pi^i - \frac{1}{m^2} \partial_i (\nabla \cdot \pi) \right) \pi^i && \dot{A}^i = \pi^i - \partial_i A^0 \\
 &&& = \pi^i - \frac{1}{m^2} \partial_i \partial_j A^j \\
 &&& \xrightarrow{\text{integrate this by parts to get a term like this}} - \int d^3x \left(\frac{1}{2} \pi^i \pi^i - \frac{1}{4} F_{ij} F_{ij} - \frac{1}{2} m^2 A^i A^i + \frac{1}{2} m^2 \cdot \left(\frac{1}{m^2} \vec{\nabla} \cdot \vec{\pi} \right)^2 \right) \\
 &&& \xrightarrow{\text{integrate this by parts to get a term like this}} = \int d^3x \left(\frac{1}{2} \pi^i \pi^i + \frac{1}{2m^2} (\vec{\nabla} \cdot \vec{\pi})^2 + \frac{1}{4} (\partial_i A^i - \partial_j A^j)^2 + \frac{1}{2} m^2 A^i A^i \right)
 \end{aligned}$$

We can see that the final result is always positive

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From

$$S = \int d^{d+1}x \left\{ -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} + \frac{1}{2} m^2 A_\mu A^\mu \right\}$$

We find that under a variation of A_y

$$SS = \int d^{d+1}x \left\{ -\frac{1}{2} F^{\mu\nu} (\partial_\mu S A_\nu - \partial_\nu S A_\mu) + m^2 A^\mu S A_\mu \right\}$$

$$= \int d^{d+1}x S A_\mu (\partial_\mu F^{\mu\nu} + m^2 A^\nu)$$

So the equations of motion are:

$$\partial_\mu (\partial^\mu A^\nu - \partial^\nu A^\mu) + m^2 A^\nu = 0 \quad (*)$$

Acting with ∂_ν , we have

$$\partial_\mu \partial_\nu (\partial^\mu A^\nu - \partial^\nu A^\mu) + m^2 \partial_\nu A^\nu = 0$$

$$\Rightarrow \boxed{\partial_\nu A^\nu = 0}$$

Using this in (*), we have the second term vanishing,
 So (*) becomes

$$(\partial_\mu \partial^\mu + m^2) A^\nu = 0$$

A plane wave in the x -direction (with definite wavelength) takes the form:

$$A^\mu = \epsilon^\mu e^{i\vec{p} \cdot \vec{x} - \omega t} \quad \vec{p} = (p_x, 0, 0)$$

$$= \epsilon^\mu e^{-i p \cdot x} \quad \text{where } p^\mu = (\omega, \vec{p})$$

Plugging in to $(\partial_\mu \partial^\mu + m^2) A^\nu = 0$, we get

$$-p^2 + m^2 = 0$$

$$\text{So: } (p^0)^2 = \vec{p}^2 + m^2 \Rightarrow p^0 = \pm \sqrt{\vec{p}^2 + m^2}$$

Plugging in to $\partial_\mu A^\mu = 0$, we get

$$p_\mu \cdot \epsilon^\mu = 0$$

Thus, we need ϵ^μ "perpendicular" to p_μ . There are 3 independent choices for ϵ^μ for each p^μ . In our case, $p^\mu = (\pm \sqrt{p_x^2}, p_x, 0, 0)$ so we could take

$$\epsilon_1^\mu = (0, 0, 1, 0), \quad \epsilon_2^\mu = (0, 0, 0, 1),$$

$$\epsilon_3^\mu = \left(\mp \frac{p_x}{m}, \sqrt{1 + \frac{p_x^2}{m^2}}, 0, 0 \right)$$

Then the general solution would be

$$A^\mu = \sum_r c_r \epsilon_r^\mu e^{i p_x \cdot x \mp \sqrt{p_x^2 + m^2} t}$$

③ P6S 2.1 : a) We have $S = \int d^4x \left\{ -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} \right\}$ with $F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$

Varying the action with respect to A_μ , we find

$$\begin{aligned}\delta S &= \int d^4x \left\{ -\frac{1}{4} F^{\mu\nu} \left\{ \partial_\mu \delta A_\nu - \partial_\nu \delta A_\mu \right\} \right\} \\ &= \int d^4x \left\{ \partial_\mu F^{\mu\nu} \delta A_\nu \right\}\end{aligned}$$

The e.o.m. is then:

$$\partial_\mu F^{\mu\nu} = 0$$

For $\nu = 0$, this gives $\partial_i F^{i0} = 0 \Rightarrow \boxed{\nabla \cdot \vec{E} = 0}$

For $\nu = j$, this gives $\partial_0 F^{0j} + \partial_j F^{00} = 0$
 $\Rightarrow -\frac{\partial E^j}{\partial t} - \partial_i \epsilon^{ijk} B^k = 0$
 $\Rightarrow \boxed{\vec{\nabla} \times \vec{B} = + \frac{\partial \vec{E}}{\partial t}}$

Note that the remaining equations are automatic from the definition of F in terms of A :

$$F_{0i} = \partial_0 A_i - \partial_i A_0 \Rightarrow E^i = -\frac{\partial A^i}{\partial t} - \nabla_i V$$

$$F_{ij} = \partial_i A_j - \partial_j A_i \Rightarrow B^i = (\nabla \times A)^i$$

These imply $\boxed{\nabla \cdot \vec{B} = 0}$ and $\boxed{\vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}}$