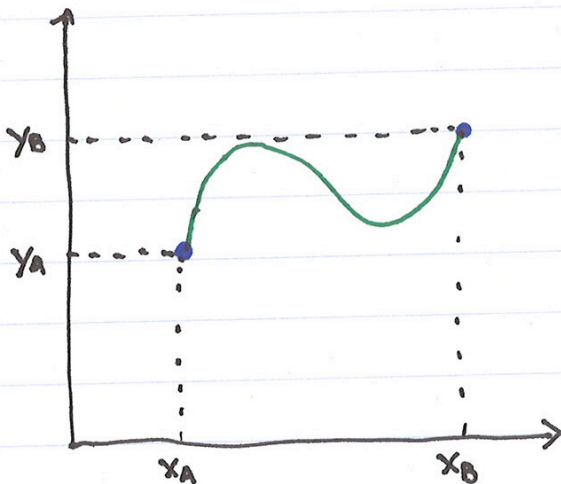


## Calculus of Variations

### The Shortest Path Between Two Points

Consider two points  $(x_A, y_A)$  and  $(x_B, y_B)$  in the  $(x, y)$  plane



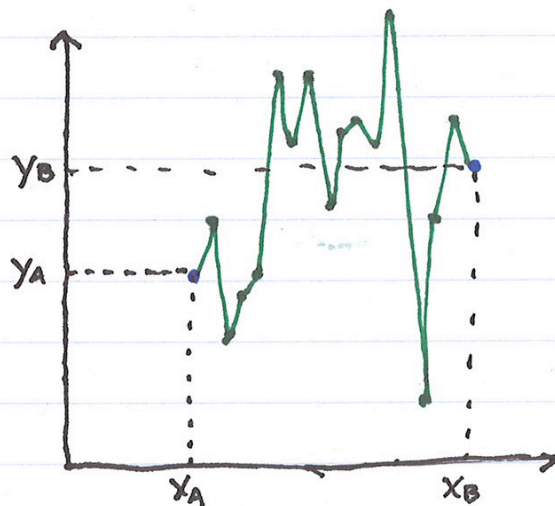
What curve  $y(x)$  has the shortest path length  $S$  between the endpoints  $(x_A, y_A)$  and  $(x_B, y_B)$ ?

How can we **prove** this?

## Calculus of Variations

### The Shortest $N+1$ -segment Path Between Two Points

Consider two points  $(x_A, y_A)$  and  $(x_B, y_B)$  in the  $(x, y)$  plane



What values of  $\{y_1, y_2, y_3, \dots, y_N\}$  lead to the shortest  $N+1$ -segment path length  $S$  between the end points  $(x_A, y_A)$  and  $(x_B, y_B)$ ?

How can we prove this?

## Calculus of Variations

The total path length  $S$  in the  $N+1$ -segment case is

$$S = S_1 + S_2 + \dots + S_N + S_{N+1} = \sum_{j=1}^{N+1} S_j$$

where  $S_j = \sqrt{(x_j - x_{j-1})^2 + (y_j - y_{j-1})^2}$

End Points  $(x_0, y_0) = (x_A, y_A)$   
 $(x_{N+1}, y_{N+1}) = (x_B, y_B)$

W.L.O.G we can set  $x_0 = y_0 = 0$   
 $x_{N+1} = l \quad y_{N+1} = h$

We take  $x_j - x_{j-1} = \Delta x = \frac{1}{N+1} l \quad \forall j = \{1, \dots, N+1\}$

$$\Rightarrow S = S(y_1, y_2, \dots, y_N) = \sum_{j=1}^{N+1} \sqrt{\Delta x^2 + (y_j - y_{j-1})^2}$$

$S$  is a function of  $y_1, y_2, \dots, y_N$   
(of  $N$  variables)



## Calculus of Variations

Our goal is to minimize  $S$  at  $S_{\min}$ .  
Or rather, to ensure that  $S$  is  
minimized at  $S(y_1, y_2, \dots, y_N) = S_{\min}$ .

As we did previously, we are free  
to choose the minimum at  $(y_1, y_2, \dots, y_N)$   
provided we parametrize arbitrary  
variations away from the minimum.

That is, we write  $Y_j = y_j + \alpha \eta_j$

so that  $S(Y_1, Y_2, \dots, Y_N) = S(y_1 + \alpha \eta_1, y_2 + \alpha \eta_2, \dots, y_N + \alpha \eta_N)$

for a variation  $\eta_1, \eta_2, \dots, \eta_N$  with fixed values  
we can consider  $S = S(\alpha)$

$$S(\alpha) = \underbrace{S(0)}_{S_{\min}} + \left. \frac{\partial S}{\partial \alpha} \right|_{\alpha=0} \alpha + \dots$$

A necessary condition for  $S(y_1, y_2, \dots, y_N) = S(\alpha=0) = S_{\min}$

$$\left. \frac{\partial S}{\partial \alpha} \right|_0 = 0$$

## Calculus of Variations

$$S(\alpha) = \sum_{j=1}^{N+1} \sqrt{\Delta x^2 + [y_j - y_{j-1} + \alpha(\eta_j - \eta_{j-1})]^2}$$

By the chain rule  $\left. \frac{\partial S}{\partial \alpha} \right|_0 = \sum_{i=1}^N \left. \frac{\partial S}{\partial y_i} \right|_0 \frac{\partial y_i}{\partial \alpha} = \sum_{i=1}^N \left. \frac{\partial S}{\partial y_i} \right|_0 \eta_i$

$$\left. \frac{\partial S}{\partial \alpha} \right|_0 = 0 = \sum_{i=1}^N \left. \frac{\partial S}{\partial y_i} \right|_0 \eta_i$$

$$\Rightarrow \left. \frac{\partial S}{\partial y_i} \right|_0 = 0 \quad \forall i \text{ individually}$$

↑ arbitrary

N Algebraic Equations for  $y_1, y_2, \dots, y_N$

Now  $\left. \frac{\partial S}{\partial y_i} \right|_0 = \sum_{j=1}^{N+1} \left[ \frac{y_j - y_{j-1}}{\sqrt{\Delta x^2 + (y_j - y_{j-1})^2}} \frac{\partial y_j}{\partial y_i} - \frac{y_j - y_{j-1}}{\sqrt{\Delta x^2 + (y_j - y_{j-1})^2}} \frac{\partial y_{j-1}}{\partial y_i} \right]$

$$= \sum_{j=1}^{N+1} \left[ \frac{y_j - y_{j-1}}{\sqrt{\Delta x^2 + (y_j - y_{j-1})^2}} \delta_{i,j} - \frac{y_j - y_{j-1}}{\sqrt{\Delta x^2 + (y_j - y_{j-1})^2}} \delta_{i,j-1} \right]$$

$$\Rightarrow \left. \frac{\partial S}{\partial y_i} \right|_0 = \frac{y_i - y_{i-1}}{\sqrt{\Delta x^2 + (y_i - y_{i-1})^2}} - \frac{y_{i+1} - y_i}{\sqrt{\Delta x^2 + (y_{i+1} - y_i)^2}} = 0$$

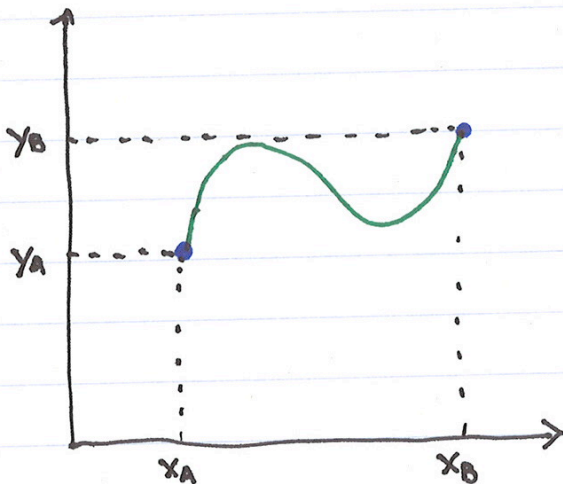
solution  $\Rightarrow y_i - y_{i-1} = y_{i+1} - y_i \quad \forall i=1, \dots, N$

$$\therefore y = \frac{h}{2} x \quad \forall (x_i, y_i)$$

## Calculus of Variations

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What curve  $y(x)$  has the shortest path length  $S$  between the endpoints  $(x_A, y_A)$  and  $(x_B, y_B)$ ?

How can we **prove** this?



## Calculus of Variations

The total path length  $S$  is

$$S = \int_A^B ds = \int_{x_A}^{x_B} dx \sqrt{1 + [y'(x)]^2}$$

since  $ds = \sqrt{dx^2 + dy^2}$

End Points  $(x_A, y_A)$  and  $(x_B, y_B)$  are fixed

W.L.O.C we can set  $x_A = y_A = 0$   
 $x_B = l \quad y_B = h$

We can choose any path  $y(x)$  we like and  $S$  depends on the entire function  $y(x)$  (actually  $y'(x)$  in this case). We should somehow denote this and we write

$$S = S[y(x)] = \int_0^l dx \sqrt{1 + [y'(x)]^2}$$

$S$  is a functional of  $y(x)$   
(of 1 function)